

Linear Algebra I

26/01/2016, Monday, 14:00 – 17:00

You are **NOT** allowed to use any type of calculators.

1 (5 + 4 + 2 + 2 + 2 = 15 pts)

Linear equations

Let A and b be given as

$$A = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 3 & 5 & 7 \\ 1 & 1 & 1 & 3 \\ 1 & 2 & 4 & 8 \end{bmatrix} \quad \text{and} \quad b = \begin{bmatrix} 0 \\ 0 \\ 2 \\ 3 \end{bmatrix}.$$

Determine

- (a) the row echelon form of A .
 - (b) the reduced row echelon form of A .
 - (c) the rank of A .
 - (d) the set of solutions of the homogeneous system $Ax = 0$.
 - (e) the set of solutions of the system $Ax = b$.
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REQUIRED KNOWLEDGE: Gauss-elimination, row operations, set of solutions, and rank.

SOLUTION:

1a: By applying row operations, we obtain:

$$\begin{aligned} & \begin{array}{l} \mathbf{2nd = 2nd - 1st} \\ \mathbf{3rd = 3rd - 1st} \\ \mathbf{4th = 4th - 1st} \end{array} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 3 & 5 & 7 \\ 1 & 1 & 1 & 3 \\ 1 & 2 & 4 & 8 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 2 & 4 & 6 \\ 0 & 0 & 0 & 2 \\ 0 & 1 & 3 & 7 \end{bmatrix} \xrightarrow{\mathbf{2nd = \frac{1}{2}2nd}} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 2 & 3 \\ 0 & 0 & 0 & 2 \\ 0 & 1 & 3 & 7 \end{bmatrix} \\ & \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 2 & 3 \\ 0 & 0 & 0 & 2 \\ 0 & 1 & 3 & 7 \end{bmatrix} \xrightarrow{\mathbf{4th = 4th - 2nd}} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 2 & 3 \\ 0 & 0 & 0 & 2 \\ 0 & 0 & 1 & 4 \end{bmatrix} \xrightarrow{\begin{array}{l} \mathbf{3rd = 4th} \\ \mathbf{4th = 3rd} \end{array}} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 2 & 3 \\ 0 & 0 & 1 & 4 \\ 0 & 0 & 0 & 2 \end{bmatrix} \\ & \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 2 & 3 \\ 0 & 0 & 1 & 4 \\ 0 & 0 & 0 & 2 \end{bmatrix} \xrightarrow{\mathbf{4th = \frac{1}{2}4th}} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 2 & 3 \\ 0 & 0 & 1 & 4 \\ 0 & 0 & 0 & 1 \end{bmatrix}. \end{aligned}$$

1b: To obtain the row reduced echelon form, we continue with the row operations

$$\begin{aligned} & \begin{array}{l} \mathbf{3rd = 3rd - 4 \times 4th} \\ \mathbf{2nd = 2nd - 3 \times 4th} \\ \mathbf{1st = 1st - 4th} \end{array} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 2 & 3 \\ 0 & 0 & 1 & 4 \\ 0 & 0 & 0 & 1 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 1 & 1 & 0 \\ 0 & 1 & 2 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \xrightarrow{\begin{array}{l} \mathbf{2nd = 2nd - 2 \times 3rd} \\ \mathbf{1st = 1st - 3rd} \end{array}} \begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \end{aligned}$$

$$\begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbf{1st} = \mathbf{1st} - \mathbf{2nd}} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}.$$

1c: As the rank equals to the number of leading zeros in the row (reduced) echelon form, we see that $\text{rank}(A) = 4$.

1d: Since the row echelon form is a nonsingular matrix, the only solution to $Ax = 0$ is the trivial solution $x = 0$.

1e: In order to find the set of solutions, we apply the same row operation in the same order to the vector b :

$$\begin{array}{c} \mathbf{2nd} = \mathbf{2nd} - \mathbf{1st} \\ \mathbf{3rd} = \mathbf{3rd} - \mathbf{1st} \\ \mathbf{4th} = \mathbf{4th} - \mathbf{1st} \end{array} \begin{bmatrix} 0 \\ 0 \\ 2 \\ 3 \end{bmatrix} \xrightarrow{\hspace{1cm}} \begin{bmatrix} 0 \\ 0 \\ 2 \\ 3 \end{bmatrix} \xrightarrow{\mathbf{2nd} = \frac{1}{2}\mathbf{2nd}} \begin{bmatrix} 0 \\ 0 \\ 2 \\ 3 \end{bmatrix} \xrightarrow{\mathbf{4th} = \mathbf{4th} - \mathbf{2nd}} \begin{bmatrix} 0 \\ 0 \\ 2 \\ 3 \end{bmatrix} \xrightarrow{\begin{array}{l} \mathbf{3rd} = \mathbf{4th} \\ \mathbf{4th} = \mathbf{3rd} \end{array}} \begin{bmatrix} 0 \\ 0 \\ 3 \\ 2 \end{bmatrix}$$

$$\begin{bmatrix} 0 \\ 0 \\ 3 \\ 2 \end{bmatrix} \xrightarrow{\mathbf{4th} = \frac{1}{2}\mathbf{4th}} \begin{bmatrix} 0 \\ 0 \\ 3 \\ 1 \end{bmatrix} \xrightarrow{\begin{array}{l} \mathbf{3rd} = \mathbf{3rd} - 4 \times \mathbf{4th} \\ \mathbf{2nd} = \mathbf{2nd} - 3 \times \mathbf{4th} \\ \mathbf{1st} = \mathbf{1st} - \mathbf{4th} \end{array}} \begin{bmatrix} -1 \\ -3 \\ -1 \\ 1 \end{bmatrix} \xrightarrow{\begin{array}{l} \mathbf{2nd} = \mathbf{2nd} - 2 \times \mathbf{3rd} \\ \mathbf{1st} = \mathbf{1st} - \mathbf{3rd} \end{array}} \begin{bmatrix} 0 \\ -1 \\ -1 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} 0 \\ -1 \\ -1 \\ 1 \end{bmatrix} \xrightarrow{\mathbf{1st} = \mathbf{1st} - \mathbf{2nd}} \begin{bmatrix} 1 \\ -1 \\ -1 \\ 1 \end{bmatrix}.$$

Therefore, $Ax = b$ has the unique solution

$$x = \begin{bmatrix} 1 \\ -1 \\ -1 \\ 1 \end{bmatrix}.$$

Let A and B be square matrices.

- (a) Show that $(A - B)(A + B) = A^2 - B^2$ if and only if $AB = BA$.
- (b) Suppose that both A and B are nonsingular. Show that $A^{-1} + B^{-1} = A^{-1}(A + B)B^{-1}$.
- (c) Suppose that $A + B$ is nonsingular. Show that $A(A + B)^{-1}B = B(A + B)^{-1}A$.

REQUIRED KNOWLEDGE: Matrix multiplication and inverse.

SOLUTION:

2a: Direct calculations yielded:

$$\begin{aligned} (A - B)(A + B) = A^2 - B^2 &\iff A^2 + AB - BA - B^2 = A^2 - B^2 \\ &\iff AB - BA = 0 \\ &\iff AB = BA. \end{aligned}$$

2b: Note that

$$\begin{aligned} A^{-1}(A + B)B^{-1} &= A^{-1}AB^{-1} + A^{-1}BB^{-1} \\ &= B^{-1} + A^{-1} = A^{-1} + B^{-1}. \end{aligned}$$

2c: Note that

$$A(A + B)^{-1}B + A(A + B)^{-1}A = A(A + B)^{-1}(B + A) = A(A + B)^{-1}(A + B) = A$$

and

$$B(A + B)^{-1}A + A(A + B)^{-1}A = (B + A)(A + B)^{-1}A = (A + B)(A + B)^{-1}A = A.$$

Consequently, we obtain

$$A(A + B)^{-1}B = B(A + B)^{-1}A.$$

Consider the matrix

$$M = \begin{bmatrix} 0 & a & b \\ -a & 0 & c \\ -b & -c & 0 \end{bmatrix}.$$

- (a) Determine the determinant of M .
- (b) For which values of a , b , and c , is the matrix M nonsingular?
- (c) Determine all values of a , b , and c such that $\text{rank}(M) = 2$.
- (d) Determine the characteristic polynomial of M .
- (e) Find the eigenvalues of M .
- (f) Without computing the eigenvectors, determine whether M is diagonalizable.

REQUIRED KNOWLEDGE: Determinant, nonsingularity, rank, eigenvalues, and diagonalization.

SOLUTION:

3a: Note that

$$\det(M) = \det\begin{pmatrix} 0 & a & b \\ -a & 0 & c \\ -b & -c & 0 \end{pmatrix} = a \det\begin{pmatrix} a & b \\ -c & 0 \end{pmatrix} - b \det\begin{pmatrix} a & b \\ 0 & c \end{pmatrix} = abc - abc = 0.$$

3b: A square matrix is nonsingular if and only if its determinant is nonzero. So, the matrix M is singular regardless of the values of a , b , and c .

3c: From 3b, it is clear that $\text{rank}(M) \leq 2$. Note that the vectors

$$\begin{bmatrix} 0 \\ -a \\ -b \end{bmatrix} \quad \text{and} \quad \begin{bmatrix} a \\ 0 \\ -c \end{bmatrix}$$

are linearly independent if and only if $a \neq 0$. Similarly, the vectors

$$\begin{bmatrix} a \\ 0 \\ -c \end{bmatrix} \quad \text{and} \quad \begin{bmatrix} b \\ c \\ 0 \end{bmatrix}$$

are linearly independent if and only if $c \neq 0$. Finally, the vectors

$$\begin{bmatrix} b \\ c \\ 0 \end{bmatrix} \quad \text{and} \quad \begin{bmatrix} 0 \\ -a \\ -b \end{bmatrix}$$

are linearly independent if and only if $b \neq 0$. Then, we have

$$a \neq 0 \quad \text{or} \quad b \neq 0 \quad \text{or} \quad c \neq 0 \implies \text{rank}(M) = 2.$$

Now, we claim that

$$\text{rank}(M) = 2 \implies a \neq 0 \quad \text{or} \quad b \neq 0 \quad \text{or} \quad c \neq 0.$$

To see this, suppose, on the contrary, that $a = b = c = 0$. Then, we have $M = 0$ and hence $\text{rank}(M) = 0$.

Consequently, we obtain

$$\text{rank}(M) = 2 \iff a \neq 0 \text{ or } b \neq 0 \text{ or } c \neq 0.$$

3d: Characteristic polynomial of M can be found as

$$\det(M - \lambda I) = \det \begin{bmatrix} -\lambda & a & b \\ -a & -\lambda & c \\ -b & -c & -\lambda \end{bmatrix} = -\lambda^3 + abc - abc - b^2\lambda - c^2\lambda - a^2\lambda = -\lambda^3 - (a^2 + b^2 + c^2)\lambda.$$

3e: Eigenvalues are the roots of the characteristic polynomial. Note that $\lambda^3 + (a^2 + b^2 + c^2)\lambda = 0$ gives $\lambda_1 = 0$ and $\lambda_{2,3} = \pm i\sqrt{a^2 + b^2 + c^2}$.

3f: We know that a matrix is diagonalizable if it has distinct eigenvalues. Since M has distinct eigenvalues, it is diagonalizable.

Consider the vector space P_4 . Let $S \subseteq P_4$ be defined as

$$S := \{p(x) \in P_4 \mid p(x) = x^3 p(\frac{1}{x})\}.$$

- (a) Show that S is a subspace of P_4 .
- (b) Find a basis for S .
- (c) Find the dimension of S .

Let $T : P_4 \rightarrow P_4$ be defined as

$$T(p(x)) := p(x) + x^2 p'(\frac{1}{x})$$

where $p'(x)$ denotes the derivative of $p(x)$.

- (d) Show that T is a linear transformation.
- (e) Determine $\ker(T)$.
- (f) Find the matrix representation of T with respect to the ordered basis $\{1, x, x^2, x^3\}$.

REQUIRED KNOWLEDGE: Subspaces, basis, dimension, linear transformations, and their matrix representations.

SOLUTION:

4a: Note that

- i. S is nonempty: The zero polynomial belongs to S .
- ii. S is closed under scalar multiplication: Let α be a scalar and $p(x) \in S$. Also, let $q(x) = \alpha p(x)$. Note that $q(x) = \alpha p(x) = \alpha x^3 p(\frac{1}{x}) = x^3 \alpha p(\frac{1}{x}) = x^3 q(\frac{1}{x})$. Thus, $q(x) \in S$.
- iii. S is closed under vector addition: Let $p(x)$ and $q(x)$ belong to S . Also, let $r(x) = p(x) + q(x)$. Note that $r(x) = p(x) + q(x) = x^3 p(\frac{1}{x}) + x^3 q(\frac{1}{x}) = x^3 (p(\frac{1}{x}) + q(\frac{1}{x})) = x^3 r(\frac{1}{x})$. Hence, $r(x) \in S$.

Consequently, S is a subspace.

4b: Let $p(x) = a + bx + cx^2 + dx^3$ belong to S . Since $p(x) = x^3 p(\frac{1}{x})$, we have

$$a + bx + cx^2 + dx^3 = x^3(a + b\frac{1}{x} + c\frac{1}{x^2} + d\frac{1}{x^3}) = d + cx + bx^2 + ax^3.$$

This means that $a = d$ and $b = c$. Thus, $p(x)$ belongs to S if and only if $p(x) = a + bx + bx^2 + ax^3$. Note that $a + bx + bx^2 + ax^3 = a(1 + x^3) + b(x + x^2)$. From this observation, it follows that $1 + x^3$ and $x + x^2$ span S . Since they are also linearly independent, we can conclude that the vectors $1 + x^3$ and $x + x^2$ form a basis for S .

4c: The dimension of a subspace equals to the cardinality (the number of elements) of the basis. Therefore, the dimension of S is 2.

4d: Let α be a scalar and $p(x), q(x) \in P_4$. Note that

$$T(\alpha p(x)) = \alpha p(x) + x^2 (\alpha p)'(\frac{1}{x}) = \alpha p(x) + x^2 \alpha p'(\frac{1}{x}) = \alpha (p(x) + x^2 p'(\frac{1}{x})) = \alpha T(p(x))$$

and

$$\begin{aligned}T(p(x) + q(x)) &= p(x) + q(x) + x^2(p + q)'(\frac{1}{x}) \\&= p(x) + q(x) + x^2(p'(\frac{1}{x}) + q'(\frac{1}{x})) \\&= p(x) + x^2p'(\frac{1}{x}) + q(x) + x^2q'(\frac{1}{x}) \\&= T(p(x)) + T(q(x)).\end{aligned}$$

Therefore, T is a linear transformation.

4e: Let $p(x) = a + bx + cx^2 + dx^3 \in \ker T$. Then, we have

$$0 = T(p(x)) = p(x) + x^2p'(\frac{1}{x}) = a + bx + cx^2 + dx^3 + x^2(b + 2c\frac{1}{x} + 3d\frac{1}{x^2}) = (a + 3d) + (b + 2c)x + (b + c)x^2 + dx^3.$$

Therefore, $p(x) = a + bx + cx^2 + dx^3 \in \ker T$ if and only if $a + 3d = b + 2c = b + c = d = 0$. By solving these equations, we obtain $a = b = c = d = 0$. Consequently, $\ker T = \{0\}$.

4f: To determine the matrix representation, we apply the transformation to the basis vectors:

$$\begin{aligned}T(1) &= 1 + x^2 \cdot 0 &&= 1 \cdot 1 + 0 \cdot x + 0 \cdot x^2 + 0 \cdot x^3 \\T(x) &= x + x^2 \cdot 1 &&= 0 \cdot 1 + 1 \cdot x + 1 \cdot x^2 + 0 \cdot x^3 \\T(x^2) &= x^2 + x^2(2\frac{1}{x}) = x^2 + 2x = 0 \cdot 1 + 2 \cdot x + 1 \cdot x^2 + 0 \cdot x^3 \\T(x^3) &= x^3 + x^2(3\frac{1}{x^2}) = x^3 + 3 = 3 \cdot 1 + 0 \cdot x + 0 \cdot x^2 + 1 \cdot x^3\end{aligned}$$

This leads to the matrix representation:

$$\begin{bmatrix} 1 & 0 & 0 & 3 \\ 0 & 1 & 2 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}.$$

Find the parabola $y = a + bx + cx^2$ that gives the best least squares approximation to the points:

$$\begin{array}{c|c|c|c|c} x & -1 & 0 & 1 & 2 \\ \hline y & 1 & -1 & 0 & 2 \end{array}$$

REQUIRED KNOWLEDGE: Least squares, and normal equations.

SOLUTION:

We can formulate the following least squares problem in order to find the best parabola of the given type:

$$\begin{bmatrix} 1 & -1 & 1 \\ 1 & 0 & 0 \\ 1 & 1 & 1 \\ 1 & 2 & 4 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \\ 0 \\ 2 \end{bmatrix}.$$

The normal equations of the least square problem $Ax = b$ are given by

$$A^T Ax = A^T b.$$

Note that

$$\begin{bmatrix} 1 & -1 & 1 \\ 1 & 0 & 0 \\ 1 & 1 & 1 \\ 1 & 2 & 4 \end{bmatrix}^T \begin{bmatrix} 1 & -1 & 1 \\ 1 & 0 & 0 \\ 1 & 1 & 1 \\ 1 & 2 & 4 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ -1 & 0 & 1 & 2 \\ 1 & 0 & 1 & 4 \end{bmatrix} \begin{bmatrix} 1 & -1 & 1 \\ 1 & 0 & 0 \\ 1 & 1 & 1 \\ 1 & 2 & 4 \end{bmatrix} = \begin{bmatrix} 4 & 2 & 6 \\ 2 & 6 & 8 \\ 6 & 8 & 18 \end{bmatrix}$$

and

$$\begin{bmatrix} 1 & -1 & 1 \\ 1 & 0 & 0 \\ 1 & 1 & 1 \\ 1 & 2 & 4 \end{bmatrix}^T \begin{bmatrix} 1 \\ -1 \\ 0 \\ 2 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ -1 & 0 & 1 & 2 \\ 1 & 0 & 1 & 4 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \\ 0 \\ 2 \end{bmatrix} = \begin{bmatrix} 2 \\ 3 \\ 9 \end{bmatrix}.$$

Thus, the normal equations are given by:

$$\begin{bmatrix} 4 & 2 & 6 \\ 2 & 6 & 8 \\ 6 & 8 & 18 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 2 \\ 3 \\ 9 \end{bmatrix}.$$

By applying Gauss elimination, we obtain

$$\begin{array}{l} \mathbf{1st} = \frac{1}{4} \times \mathbf{1st} \\ \mathbf{2nd} = \mathbf{2nd} - 2 \times \mathbf{1st} \\ \mathbf{3rd} = \mathbf{3rd} - 6 \times \mathbf{1st} \end{array} \rightarrow \begin{bmatrix} 1 & \frac{1}{2} & \frac{3}{2} & \vdots & \frac{1}{2} \\ 0 & 5 & 5 & \vdots & 2 \\ 0 & 5 & 9 & \vdots & 6 \end{bmatrix}$$

$$\begin{array}{l} \mathbf{3rd} = \mathbf{3rd} - \mathbf{2nd} \end{array} \rightarrow \begin{bmatrix} 1 & \frac{1}{2} & \frac{3}{2} & \vdots & \frac{1}{2} \\ 0 & 5 & 5 & \vdots & 2 \\ 0 & 0 & 4 & \vdots & 4 \end{bmatrix}$$

$$\begin{array}{l} \mathbf{3rd} = \frac{1}{5} \times \mathbf{3rd} \\ \mathbf{4th} = \frac{1}{4} \times \mathbf{4th} \end{array} \rightarrow \begin{bmatrix} 1 & \frac{1}{2} & \frac{3}{2} & \vdots & \frac{1}{2} \\ 0 & 1 & 1 & \vdots & \frac{2}{5} \\ 0 & 0 & 1 & \vdots & 1 \end{bmatrix}.$$

This leads to the solution

$$\begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} -\frac{7}{10} \\ -\frac{3}{5} \\ 1 \end{bmatrix}.$$

Therefore, the best parabola is given by

$$y = -\frac{7}{10} - \frac{3}{5}x + x^2.$$

Consider the matrix

$$A = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{bmatrix}.$$

- (a) Show that 1 is an eigenvalue of A .
 (b) Determine all eigenvalues of A .
 (c) Find a matrix T such that $T^{-1}AT$ is diagonal.

REQUIRED KNOWLEDGE: **Eigenvalues, eigenvectors, and diagonalization.**

SOLUTION:

6a: The matrix A has an eigenvalue λ if and only if $\det(A - \lambda I) = 0$. Note that

$$\det(A - I) = \det\left(\begin{bmatrix} 0 & 1 & 1 \\ 0 & -1 & 1 \\ 0 & -1 & -1 \end{bmatrix}\right) = 0$$

as the first column consists entirely of zeros. Therefore, 1 is an eigenvalue of A .

6b: Note that

$$\det(A - \lambda I) = \det\left(\begin{bmatrix} 1 - \lambda & 1 & 1 \\ 0 & -\lambda & 1 \\ 0 & -1 & -\lambda \end{bmatrix}\right) = (1 - \lambda) \det\left(\begin{bmatrix} -\lambda & 1 \\ -1 & -\lambda \end{bmatrix}\right) = (1 - \lambda)(\lambda^2 + 1).$$

This results in the eigenvalues $\lambda_1 = 1$, $\lambda_{2,3} = \pm i$.

6c: In order to find a diagonalizer, we need to compute an eigenvector for each eigenvalue:

i. $\lambda_1 = 1$: Note that

$$0 = (A - I)x_1 = \begin{bmatrix} 0 & 1 & 1 \\ 0 & -1 & 1 \\ 0 & -1 & -1 \end{bmatrix} x_1$$

results in

$$x_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}.$$

ii. $\lambda_2 = i$: Note that

$$0 = (A - iI)x_2 = \begin{bmatrix} 1 - i & 1 & 1 \\ 0 & -i & 1 \\ 0 & -1 & -i \end{bmatrix} x_2$$

results in

$$x_2 = \begin{bmatrix} -i \\ 1 \\ i \end{bmatrix}.$$

iii. $\lambda_3 = -i$: Note that

$$0 = (A - iI)x_3 = \begin{bmatrix} 1 + i & 1 & 1 \\ 0 & i & 1 \\ 0 & -1 & i \end{bmatrix} x_3$$

results in

$$x_3 = \begin{bmatrix} i \\ 1 \\ -i \end{bmatrix}.$$

Therefore, one can take

$$T = [x_1 \quad x_2 \quad x_3] = \begin{bmatrix} 1 & -i & i \\ 0 & 1 & 1 \\ 0 & i & -i \end{bmatrix}.$$

To verify that T is a diagonalizer, note that

$$AT = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{bmatrix} \begin{bmatrix} 1 & -i & i \\ 0 & 1 & 1 \\ 0 & i & -i \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 \\ 0 & i & -i \\ 0 & -1 & -1 \end{bmatrix}$$

and

$$T \begin{bmatrix} 1 & 0 & 0 \\ 0 & i & 0 \\ 0 & 0 & -i \end{bmatrix} = \begin{bmatrix} 1 & -i & i \\ 0 & 1 & 1 \\ 0 & i & -i \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & i & 0 \\ 0 & 0 & -i \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 \\ 0 & i & -i \\ 0 & -1 & -1 \end{bmatrix}.$$
